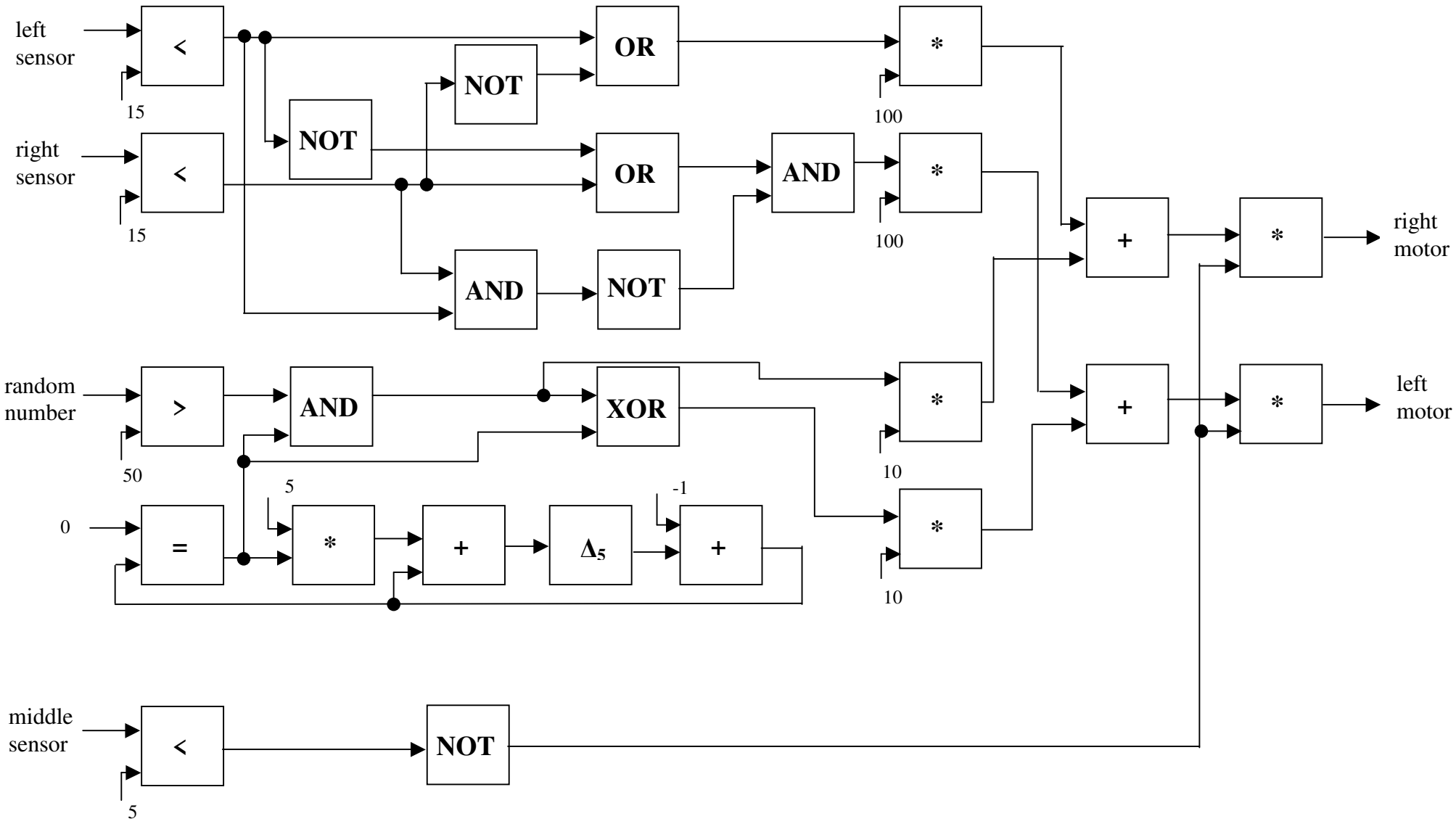
left sensor
<
15
NOT
OR
*
100
right sensor
<
15
NOT
OR
AND
*
100
AND
NOT
+
*
right motor
random number
>
50
AND
XOR
*
10
+
*
left motor
0
=
5
*
+
Δ5
-1
+
*
10
middle sensor
<
5
NOT