



## 6.867 Machine learning: lecture 2

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## Topics

- The learning problem
  - hypothesis class, estimation algorithm
  - loss and estimation criterion
  - sampling, empirical and expected losses
- Regression, example
- Linear regression
  - estimation, errors, analysis



## Review: the learning problem

- Recall the image (face) recognition problem



- **Hypothesis class:** we consider some *restricted* set  $\mathcal{F}$  of mappings  $f : \mathcal{X} \rightarrow \mathcal{L}$  from images to labels
- **Estimation:** on the basis of a training set of examples and labels,  $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\}$ , we find an estimate  $\hat{f} \in \mathcal{F}$
- **Evaluation:** we measure how well  $\hat{f}$  *generalizes* to yet unseen examples, i.e., whether  $\hat{f}(\mathbf{x}_{new})$  agrees with  $y_{new}$



## Hypotheses and estimation

- We used a simple linear classifier, a parameterized mapping  $f(\mathbf{x}; \theta)$  from images  $\mathcal{X}$  to labels  $\mathcal{L}$ , to solve a binary image classification problem (2's vs 3's):

$$\hat{y} = f(\mathbf{x}; \theta) = \text{sign}(\theta \cdot \mathbf{x})$$

where  $\mathbf{x}$  is a pixel image and  $\hat{y} \in \{-1, 1\}$ .

- The parameters  $\theta$  were adjusted on the basis of the training examples and labels according to a simple mistake driven update rule (written here in a vector form)

$$\theta \leftarrow \theta + y_i \mathbf{x}_i, \quad \text{whenever } y_i \neq \text{sign}(\theta \cdot \mathbf{x}_i)$$

- The update rule attempts to minimize the number of errors that the classifier makes on the training examples



## Estimation criterion

- We can formulate the estimation problem more explicitly by defining a *zero-one loss*:

$$\text{Loss}(y, \hat{y}) = \begin{cases} 0, & y = \hat{y} \\ 1, & y \neq \hat{y} \end{cases}$$

so that

$$\frac{1}{n} \sum_{i=1}^n \text{Loss}(y_i, \hat{y}_i) = \frac{1}{n} \sum_{i=1}^n \text{Loss}(y_i, f(\mathbf{x}_i; \theta))$$

gives the fraction of prediction errors on the training set.

- This is a function of the parameters  $\theta$  and we can try to minimize it directly.



## Estimation criterion cont'd

- We have reduced the estimation problem to a minimization problem

$$\text{find } \theta \text{ that minimizes } \overbrace{\frac{1}{n} \sum_{i=1}^n \text{Loss}(y_i, f(\mathbf{x}_i; \theta))}^{\text{empirical loss}}$$



## Estimation criterion cont'd

- We have reduced the estimation problem to a minimization problem

find  $\theta$  that minimizes  $\frac{1}{n} \sum_{i=1}^n \text{Loss}(y_i, f(\mathbf{x}_i; \theta))$

empirical loss

- valid for any parameterized class of mappings from examples to predictions
- valid when the predictions are discrete labels, real valued, or other provided that the loss is defined appropriately
- may be ill-posed (under-constrained) as stated



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empirical loss

- valid for any parameterized class of mappings from examples to predictions
- valid when the predictions are discrete labels, real valued, or other provided that the loss is defined appropriately
- may be ill-posed (under-constrained) as stated
- But why is it sensible to minimize the *empirical loss* in the first place since we are only interested in the performance on new examples?



## Training and test performance: sampling

- We assume that each training *and* test example-label pair,  $(\mathbf{x}, y)$ , is drawn *independently at random* from the *same* but unknown population of examples and labels.
- We can represent this population as a joint probability distribution  $P(\mathbf{x}, y)$  so that each training/test example is a *sample* from this distribution  $(\mathbf{x}_i, y_i) \sim P$



## Training and test performance: sampling

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$$\text{Empirical (training) loss} = \frac{1}{n} \sum_{i=1}^n \text{Loss}(y_i, f(\mathbf{x}_i; \theta))$$

$$\text{Expected (test) loss} = E_{(\mathbf{x}, y) \sim P} \{ \text{Loss}(y, f(\mathbf{x}; \theta)) \}$$

- The training loss based on a few sampled examples and labels serves as a proxy for the test performance measured over the whole population.



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## Regression

- The goal is to make quantitative (real valued) predictions on the basis of a (vector of) features or attributes
- Example: predicting vehicle fuel efficiency (mpg) from 8 attributes

y	x				...
	cyls	disp	hp	weight	
18.0	8	307.0	130.00	3504	...
26.0	4	97.00	46.00	1835	...
33.5	4	98.00	83.00	2075	...
...					



## Regression

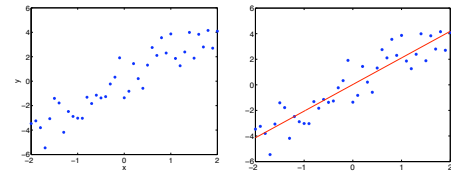
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- We need to
  - specify the class of functions (e.g., linear)
  - select how to measure prediction loss
  - solve the resulting minimization problem



## Linear regression



- We begin by considering linear regression (easy to extend to more complex predictions later on)

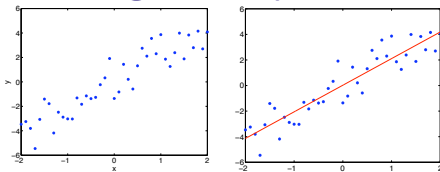
$$f: \mathcal{R} \rightarrow \mathcal{R} \quad f(x; \mathbf{w}) = w_0 + w_1 x$$

$$f: \mathcal{R}^d \rightarrow \mathcal{R} \quad f(\mathbf{x}; \mathbf{w}) = w_0 + w_1 x_1 + \dots + w_d x_d$$

where  $\mathbf{w} = [w_0, w_1, \dots, w_d]^T$  are *parameters* we need to set.



## Linear regression: squared loss



$$f: \mathcal{R} \rightarrow \mathcal{R} \quad f(x; \mathbf{w}) = w_0 + w_1 x$$

$$f: \mathcal{R}^d \rightarrow \mathcal{R} \quad f(\mathbf{x}; \mathbf{w}) = w_0 + w_1 x_1 + \dots + w_d x_d$$

- We can measure the prediction loss in terms of squared error,  $\text{Loss}(y, \hat{y}) = (y - \hat{y})^2$ , so that the empirical loss on  $n$  training samples becomes *mean squared error*

$$J_n(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n (y_i - f(\mathbf{x}_i; \mathbf{w}))^2$$



## Linear regression: estimation

- We have to minimize the *empirical* squared loss

$$\begin{aligned} J_n(\mathbf{w}) &= \frac{1}{n} \sum_{i=1}^n (y_i - f(\mathbf{x}_i; \mathbf{w}))^2 \\ &= \frac{1}{n} \sum_{i=1}^n (y_i - w_0 - w_1 x_i)^2 \quad (\text{1-dim}) \end{aligned}$$

By setting the derivatives with respect to  $w_1$  and  $w_0$  to zero, we get necessary conditions for the “optimal” parameter values

$$\frac{\partial}{\partial w_1} J_n(\mathbf{w}) = 0$$

$$\frac{\partial}{\partial w_0} J_n(\mathbf{w}) = 0$$



## Optimality conditions: derivation

$$\frac{\partial}{\partial w_1} J_n(\mathbf{w}) = \frac{\partial}{\partial w_1} \frac{1}{n} \sum_{i=1}^n (y_i - w_0 - w_1 x_i)^2$$



## Optimality conditions: derivation

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## Optimality conditions: derivation

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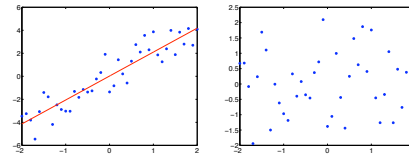


## Interpretation

- If we denote the prediction error as  $\epsilon_i = (y_i - w_0 - w_1 x_i)$  then the optimality conditions can be written as

$$\frac{1}{n} \sum_{i=1}^n \epsilon_i x_i = 0, \quad \frac{1}{n} \sum_{i=1}^n \epsilon_i = 0$$

Thus the prediction error is uncorrelated with any linear function of the inputs



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$$\frac{1}{n} \sum_{i=1}^n \epsilon_i x_i = 0, \quad \frac{1}{n} \sum_{i=1}^n \epsilon_i = 0$$

Thus the prediction error is uncorrelated with any linear function of the inputs

but not with a quadratic function of the inputs

$$\frac{1}{n} \sum_{i=1}^n \epsilon_i x_i^2 \neq 0 \quad (\text{in general})$$



## Linear regression: matrix notation

- We can express the solution a bit more generally by resorting to a matrix notation

$$\mathbf{y} = \begin{bmatrix} y_1 \\ \dots \\ y_n \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & x_1 \\ \dots & \dots \\ 1 & x_n \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}$$

so that

$$\begin{aligned} \frac{1}{n} \sum_{t=1}^n (y_t - w_0 - w_1 x_t)^2 &= \frac{1}{n} \left\| \begin{bmatrix} y_1 \\ \dots \\ y_n \end{bmatrix} - \begin{bmatrix} 1 & x_1 \\ \dots & \dots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} \right\|^2 \\ &= \frac{1}{n} \|\mathbf{y} - \mathbf{X}\mathbf{w}\|^2 \end{aligned}$$



### Linear regression: solution

By setting the derivatives of  $\|y - Xw\|^2/n$  to zero, we get the same optimality conditions as before, now expressed in a matrix form

$$\frac{\partial}{\partial w} \frac{1}{n} \|y - Xw\|^2 = \frac{\partial}{\partial w} \frac{1}{n} (y - Xw)^T (y - Xw)$$



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$$\begin{aligned} \frac{\partial}{\partial w} \frac{1}{n} \|y - Xw\|^2 &= \frac{\partial}{\partial w} \frac{1}{n} (y - Xw)^T (y - Xw) \\ &= \frac{2}{n} X^T (y - Xw) \end{aligned}$$



### Linear regression: solution

By setting the derivatives of  $\|y - Xw\|^2/n$  to zero, we get the same optimality conditions as before, now expressed in a matrix form

$$\begin{aligned} \frac{\partial}{\partial w} \frac{1}{n} \|y - Xw\|^2 &= \frac{\partial}{\partial w} \frac{1}{n} (y - Xw)^T (y - Xw) \\ &= \frac{2}{n} X^T (y - Xw) \\ &= \frac{2}{n} (X^T y - X^T X w) = 0 \end{aligned}$$

which gives

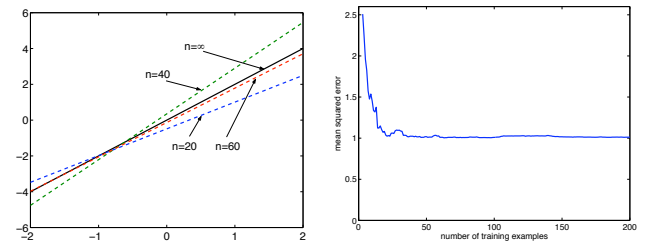
$$\hat{w} = (X^T X)^{-1} X^T y$$

- The solution is a linear function of the outputs  $y$



### Linear regression: generalization

- As the number of training examples increases our solution gets "better"



We'd like to understand the error a bit better



### Linear regression: types of errors

- **Structural error** measures the error introduced by the limited function class (infinite training data):

$$\min_{w_0, w_1} E_{(x,y) \sim P} (y - w_0 - w_1 x)^2 = E_{(x,y) \sim P} (y - w_0^* - w_1^* x)^2$$

where  $(w_0^*, w_1^*)$  are the optimal linear regression parameters.



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where  $(w_0^*, w_1^*)$  are the optimal linear regression parameters.

- **Approximation error** measures how close we can get to the optimal linear predictions with limited training data:

$$E_{(x,y) \sim P} (w_0^* + w_1^* x - \hat{w}_0 - \hat{w}_1 x)^2$$

where  $(\hat{w}_0, \hat{w}_1)$  are the parameter estimates based on a small training set (therefore themselves random variables).



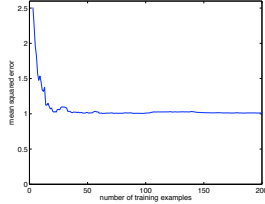
## Linear regression: error decomposition

- The expected error of our linear regression function decomposes into the sum of structural and approximation errors

$$E_{(x,y) \sim P} (y - \hat{w}_0 - \hat{w}_1 x)^2 =$$

$$E_{(x,y) \sim P} (y - w_0^* - w_1^* x)^2 +$$

$$E_{(x,y) \sim P} (w_0^* + w_1^* x - \hat{w}_0 - \hat{w}_1 x)^2$$



## Error decomposition: derivation

$$E_{(x,y) \sim P} (y - \hat{w}_0 - \hat{w}_1 x)^2$$

$$= E_{(x,y) \sim P} ((y - w_0^* - w_1^* x) + (w_0^* + w_1^* x - \hat{w}_0 - \hat{w}_1 x))^2$$

$$= E_{(x,y) \sim P} (y - w_0^* - w_1^* x)^2$$

$$+ E_{(x,y) \sim P} 2(y - w_0^* - w_1^* x)(w_0^* + w_1^* x - \hat{w}_0 - \hat{w}_1 x)$$

$$+ E_{(x,y) \sim P} (w_0^* + w_1^* x - \hat{w}_0 - \hat{w}_1 x)^2$$

The second term has to be zero since the error  $(y - w_0^* - w_1^* x)$  of the best linear predictor is necessarily uncorrelated with any linear function of the input including  $(w_0^* + w_1^* x - \hat{w}_0 - \hat{w}_1 x)$