



Machine learning: lecture 20

Tommi S. Jaakkola

MIT CSAIL

tommi@csail.mit.edu



Topics

- Representation and graphical models
 - examples
- Bayesian networks
 - examples, specification
 - graphs and independence
 - associated distribution

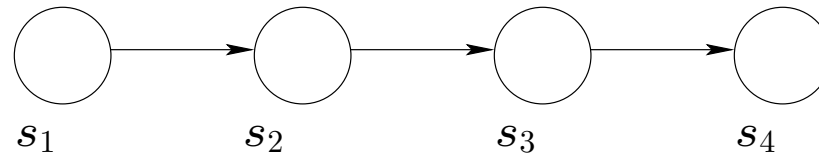


What is a good representation?

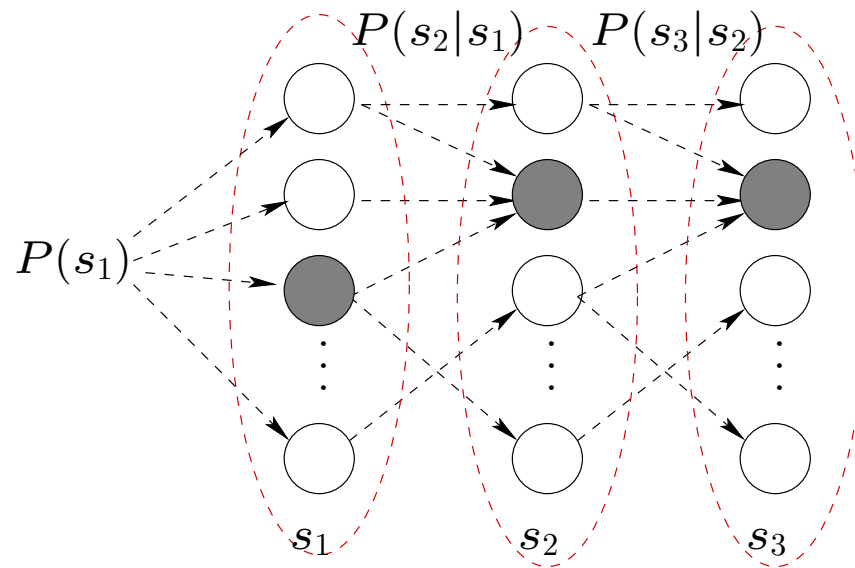
- Properties of good representations
 1. Explicit
 2. Modular
 3. Permits efficient computation
 4. etc.

Representation: explicit

- Representation in terms of variables and dependencies (a graphical model):



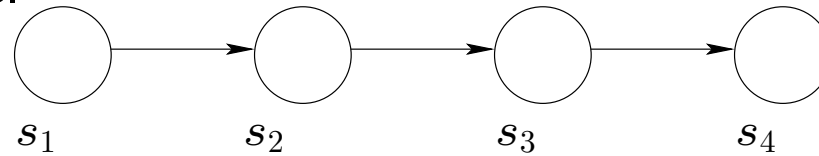
- Representation in terms of state transitions (transition diagram)



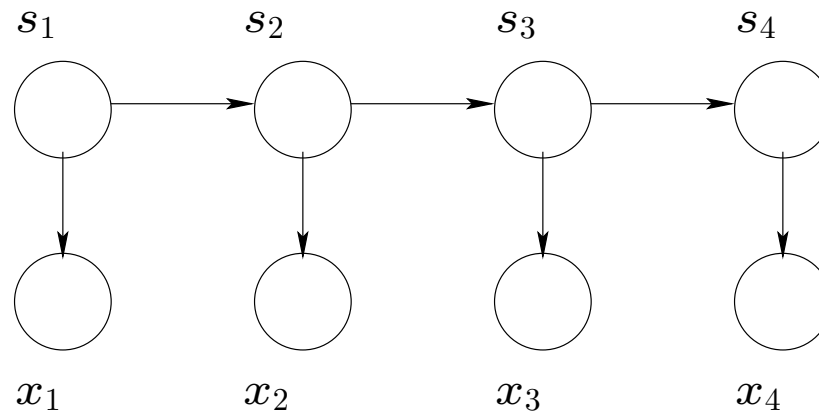
Representation: modular

- We can easily add/remove components of the model

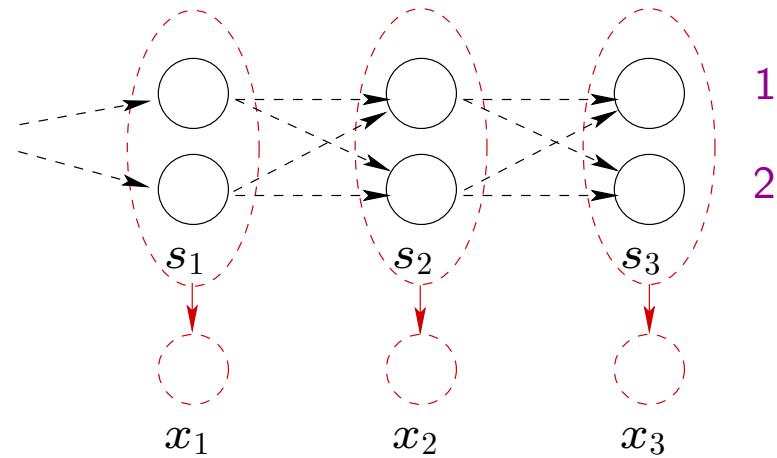
Markov model



Hidden Markov model



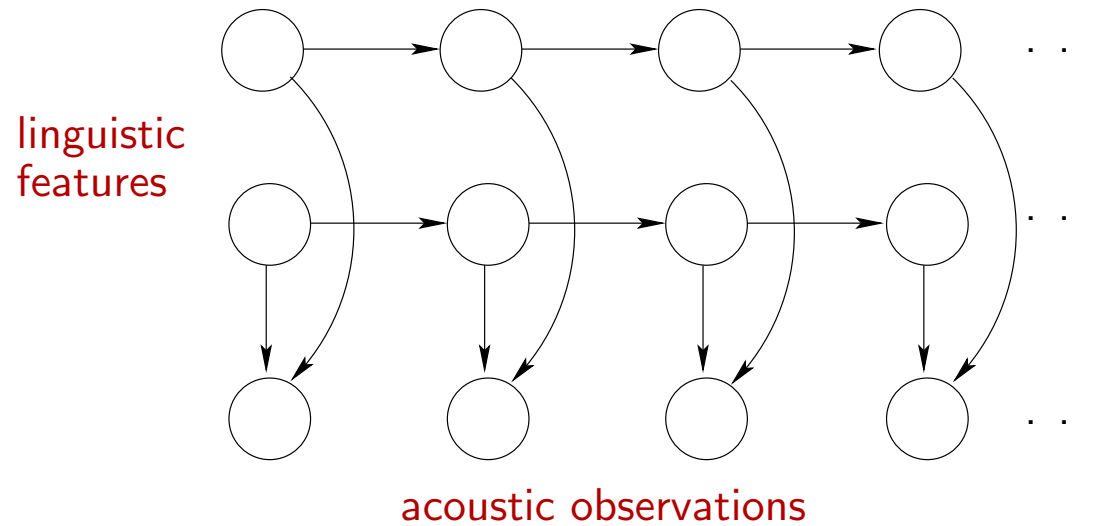
Representation: efficient computation



- Posterior marginals (forward-backward)
- Max-probabilities (viterbi)

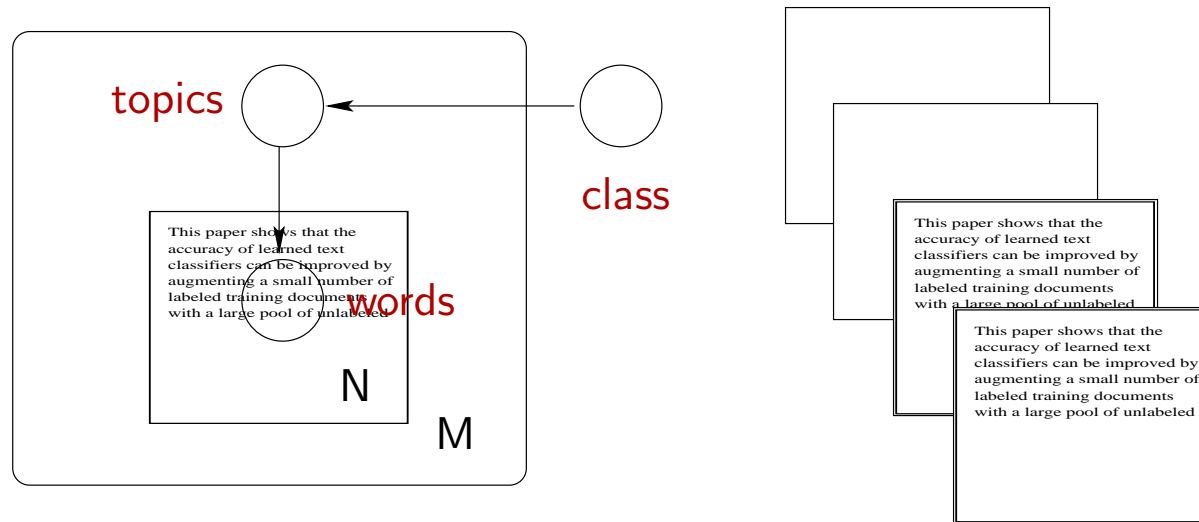
Graphical models: examples

- Factorial Hidden Markov model as a Bayesian network (directed graphical model)



Graphical models: examples

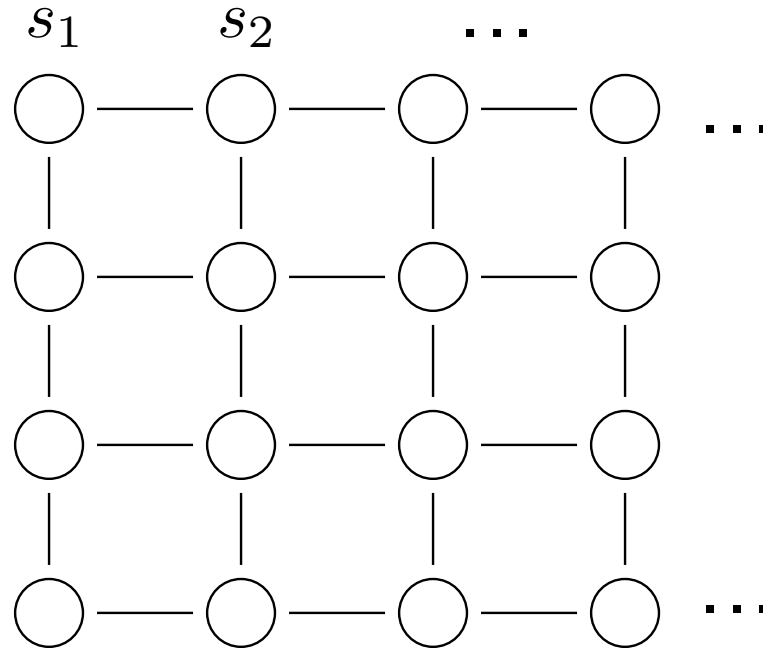
- Plates and repeated sampling



- each document has N words, sampled from a distribution that depends on the choice of topics
- the topics for each document are sampled from a class conditional distribution

Graphical models: examples

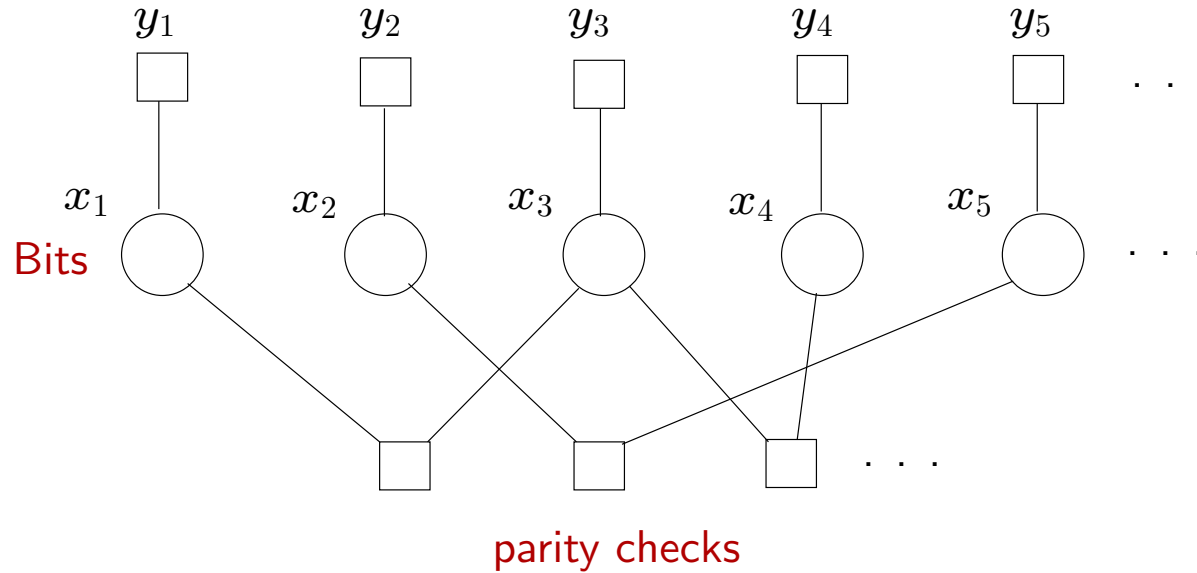
- Lattice models (e.g., Ising model) as a Markov random field



- symmetric interactions (e.g., alignment of two nearby spins is energetically favorable)

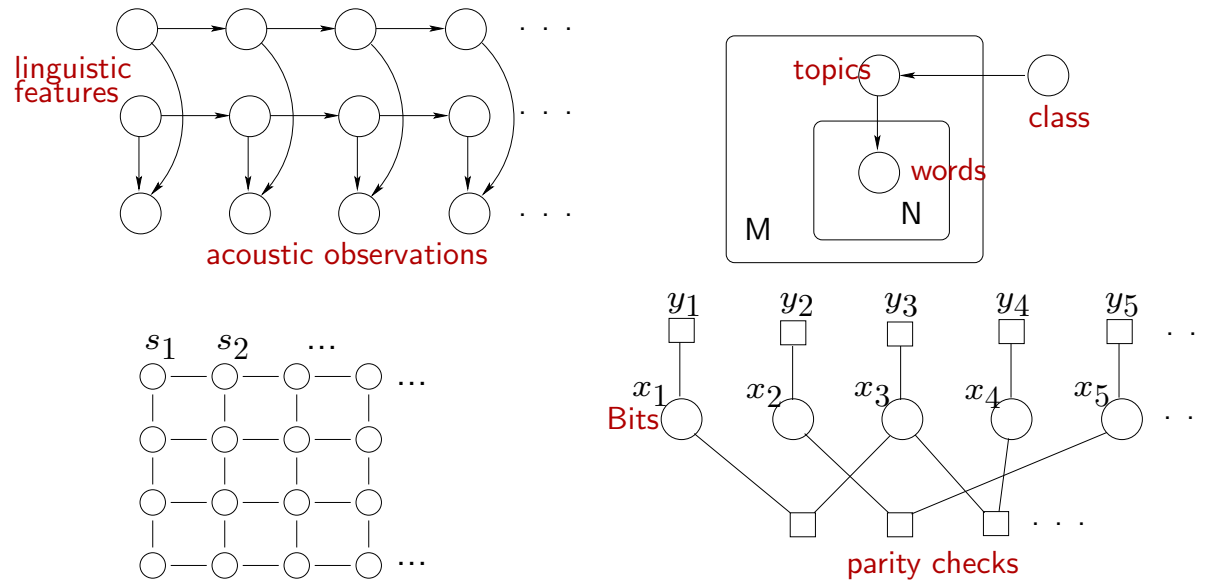
Graphical models: examples

- Factor graphs and codes (information theory)



- circles denote variables while the squares are factors (functions) that constrain the values of the variables

Graphical models

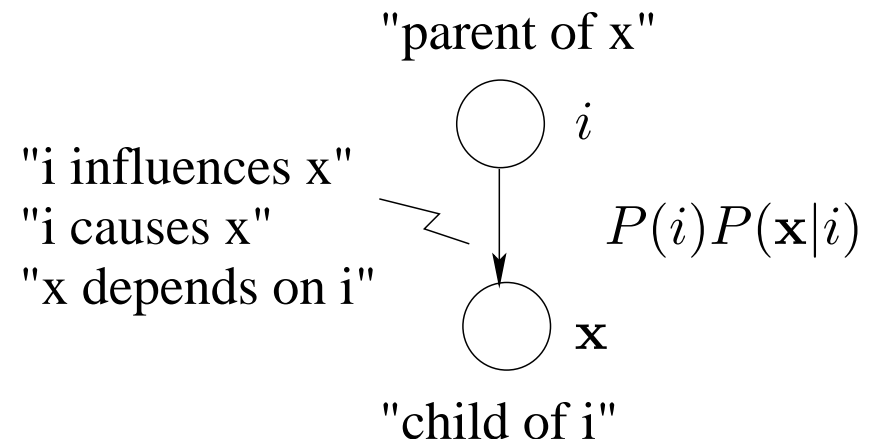


- Graph semantics:
graph \Rightarrow separation properties \Rightarrow independence
- Association with probability distributions:
independence \Rightarrow family of distributions
- Inference and estimation:
graph structure \Rightarrow efficient computation

Bayesian networks

- Bayesian networks are directed acyclic graphs, where the nodes represent variables and directed edges capture dependencies

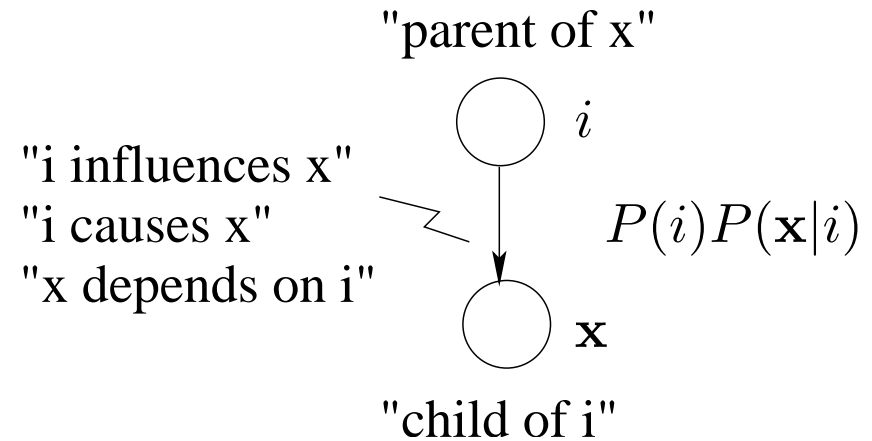
A mixture model as a Bayesian network



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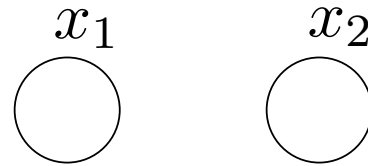
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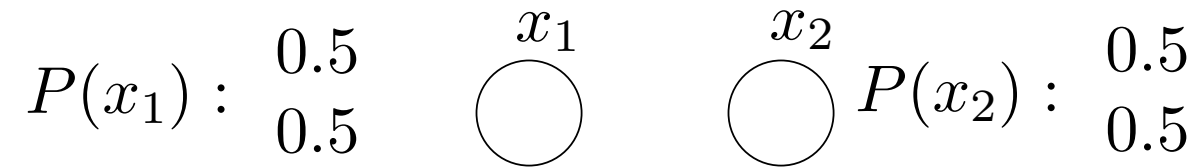
Example

- A simple Bayesian network: coin tosses



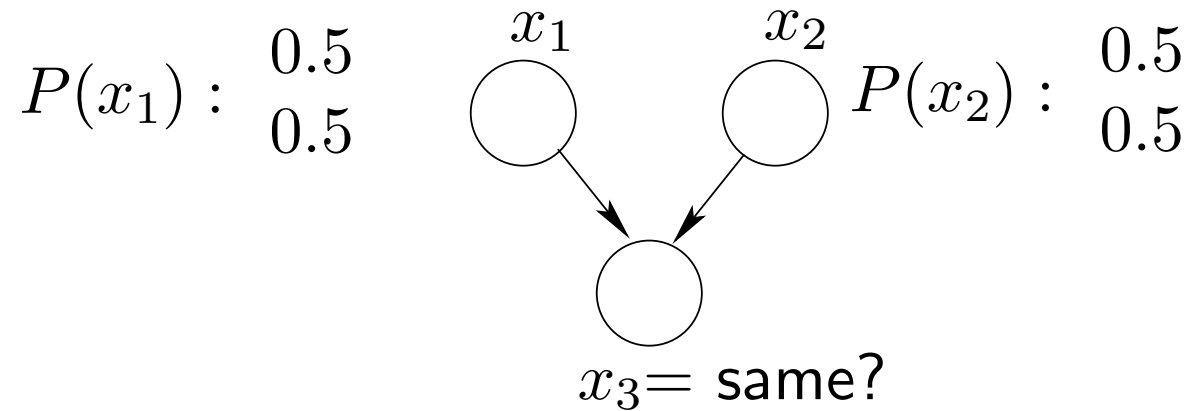
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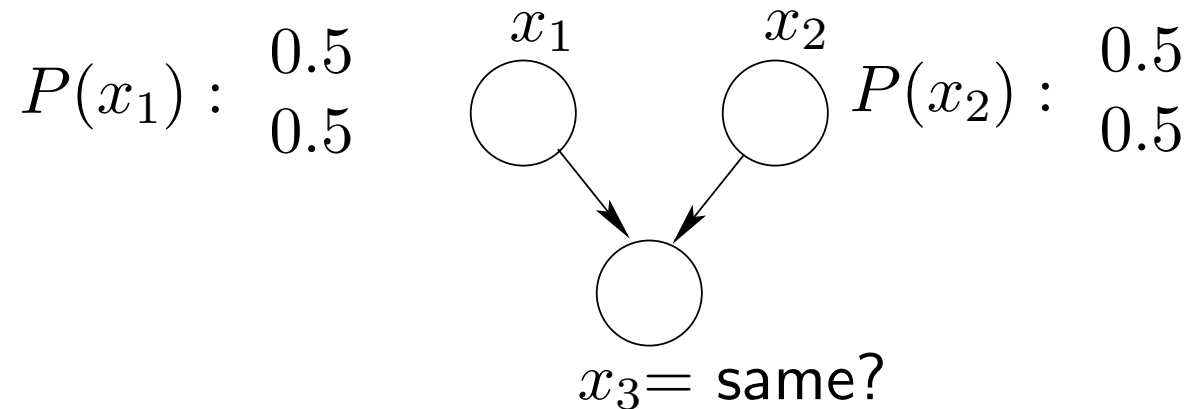
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Example

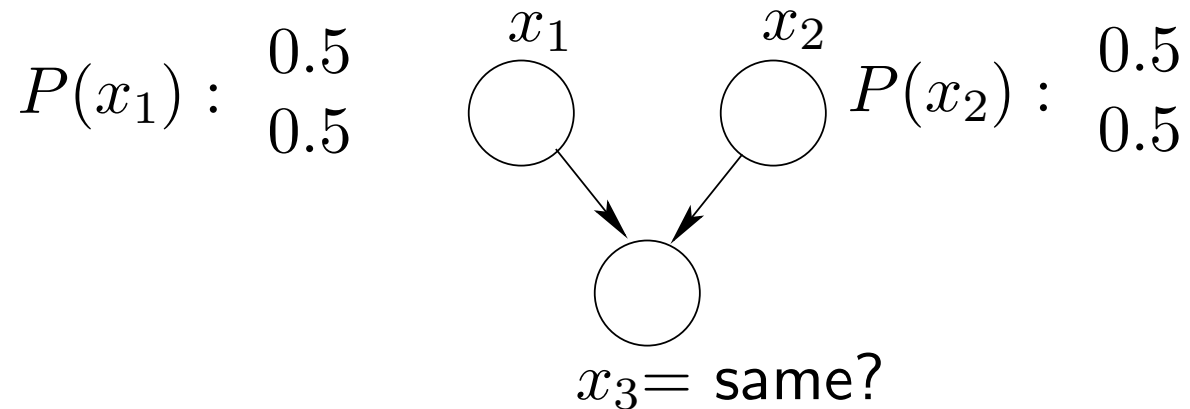
- A simple Bayesian network: coin tosses



		<i>hh</i>	<i>ht</i>	<i>th</i>	<i>tt</i>
$P(x_3 x_1, x_2) :$	<i>y</i>	1.0	0.0	0.0	1.0
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Example

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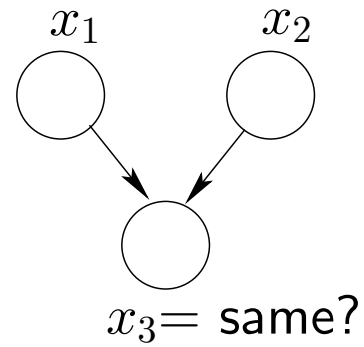


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- Two levels of description
 1. graph structure (dependencies, independencies)
 2. associated probability distribution

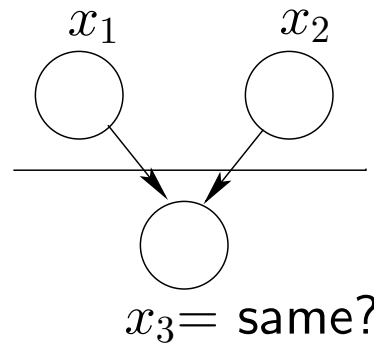
Example cont'd

- What can the graph alone tell us?



Example cont'd

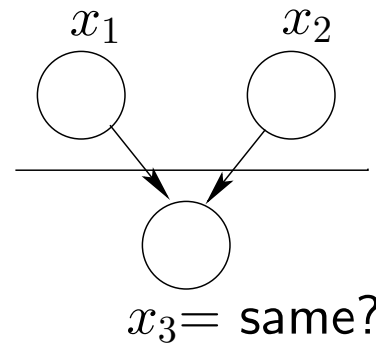
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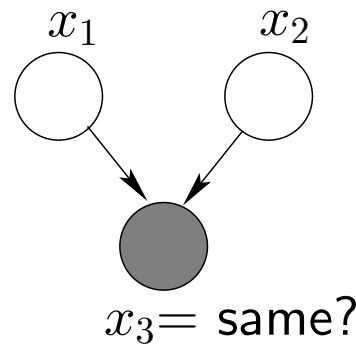
- x_1 and x_2 are *marginally independent*

Example cont'd

- What can the graph alone tell us?



- x_1 and x_2 are *marginally independent*



- x_1 and x_2 become *dependent* if we know x_3
(the dependence concerns our beliefs about the outcomes)

Traffic example

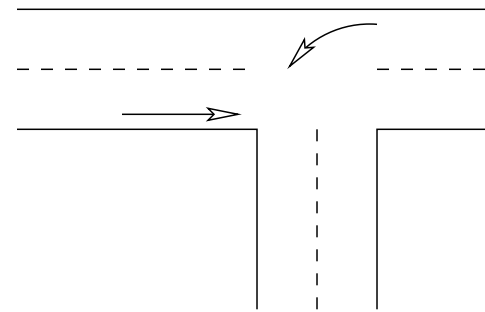
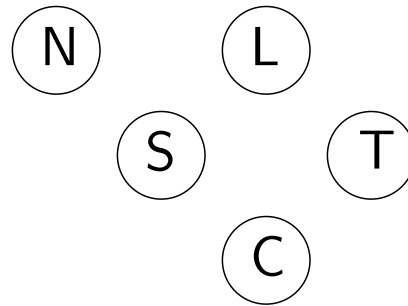
N = X is nice?

L = traffic light

S = X decides to stop?

T = the other car turns left?

C = crash?



Traffic example

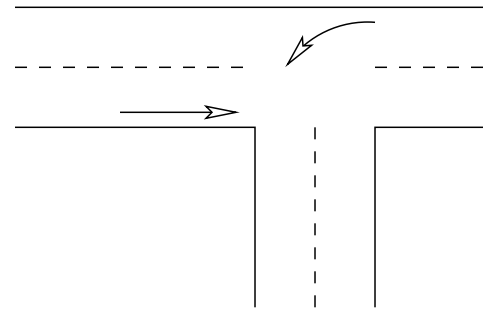
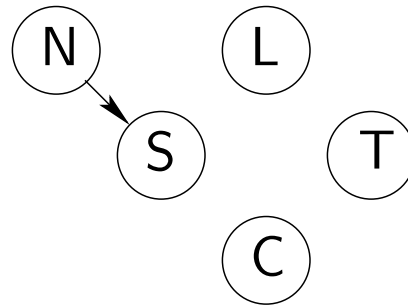
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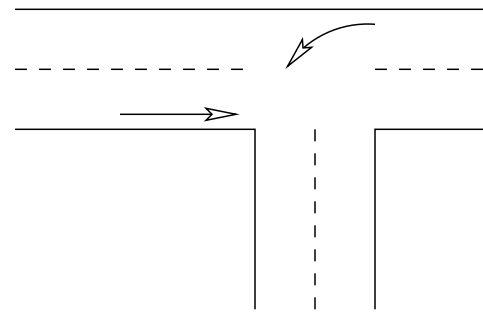
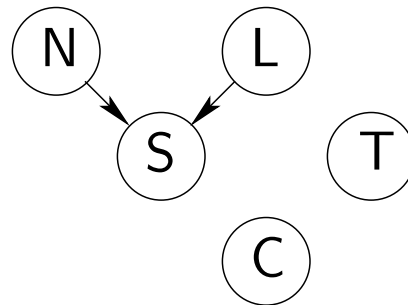
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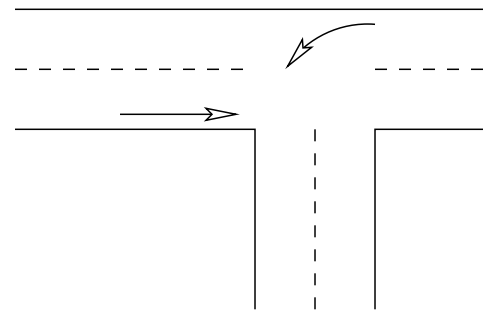
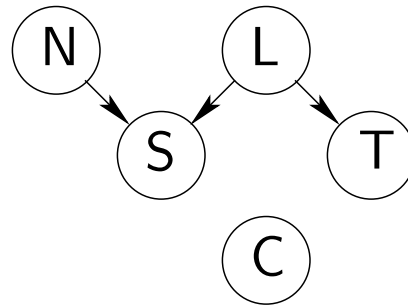
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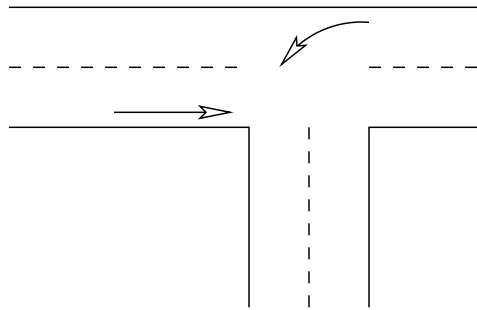
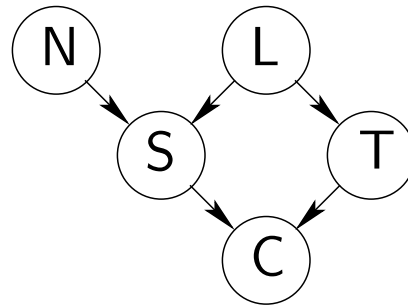
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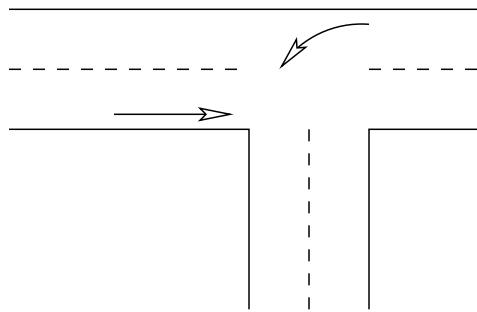
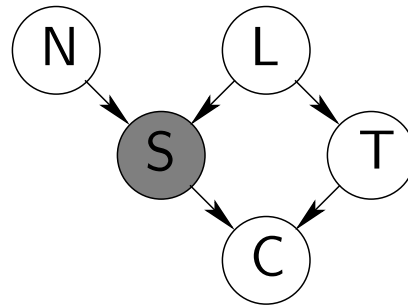
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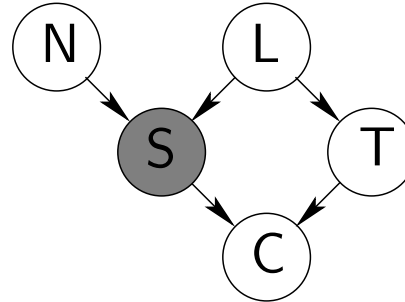
C = crash?



- If we only know that X decided to stop, can X's character (variable N) tell us anything about the other car turning (variable T)?

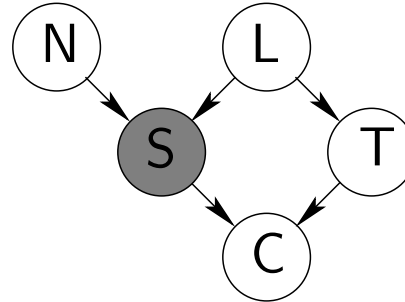
Graph, independence, d-separation

- Are N and T independent given S ?



Graph, independence, d-separation

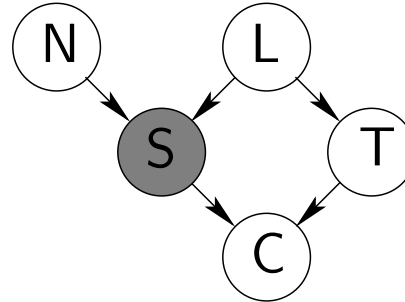
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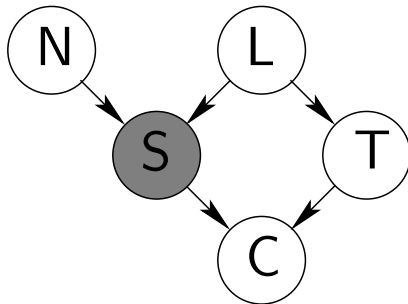
Definition: Variables N and T are D-separated given S if S separates them in the moralized ancestral graph

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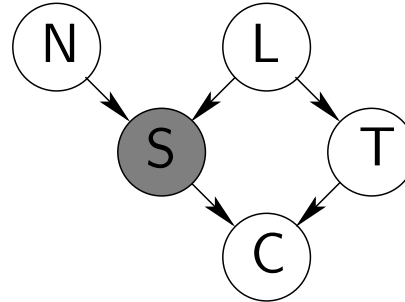
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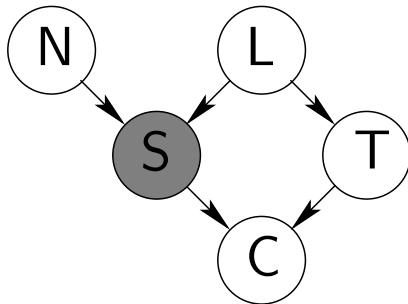
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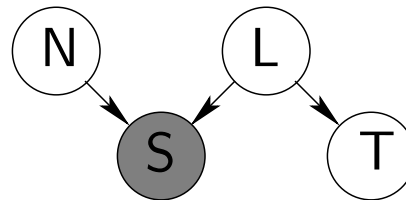
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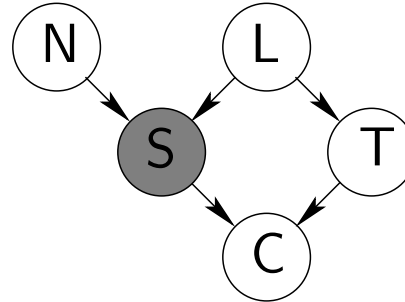
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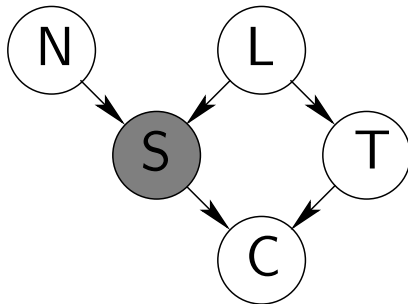
ancestral

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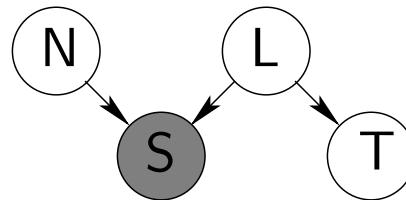
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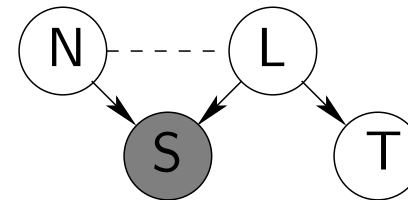
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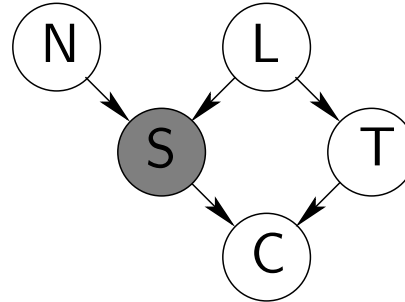
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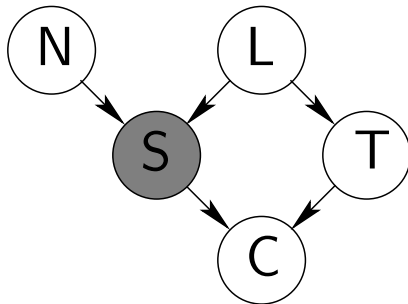
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Graph, independence, d-separation

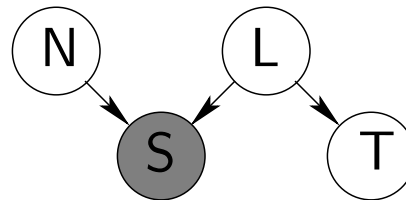
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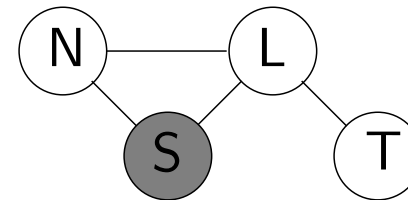
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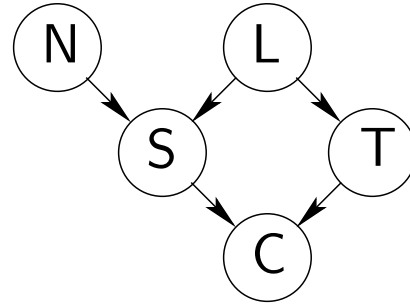


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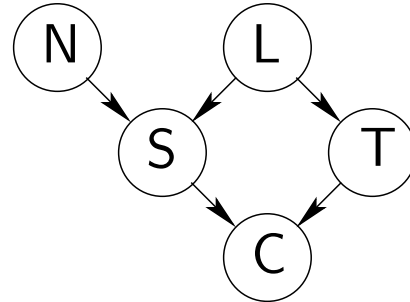
moralized ancestral

Graphs and distributions



- A graph is a compact representation of a large collection of independence properties

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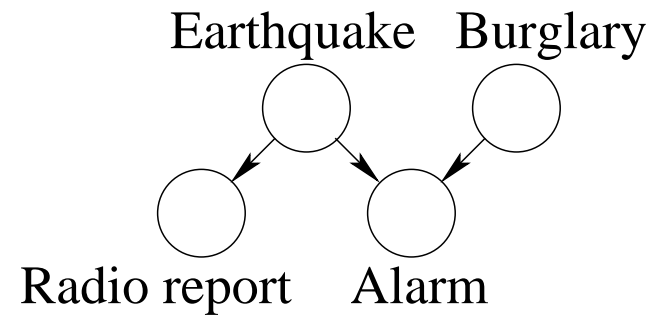
Theorem: Any probability distribution that is consistent with a directed graph G has to factor according to “node given parents”:

$$P(\mathbf{x}|G) = \prod_{i=1}^d P(x_i|\mathbf{x}_{pa_i})$$

where \mathbf{x}_{pa_i} are the *parents* of x_i and d is the number of nodes (variables) in the graph.

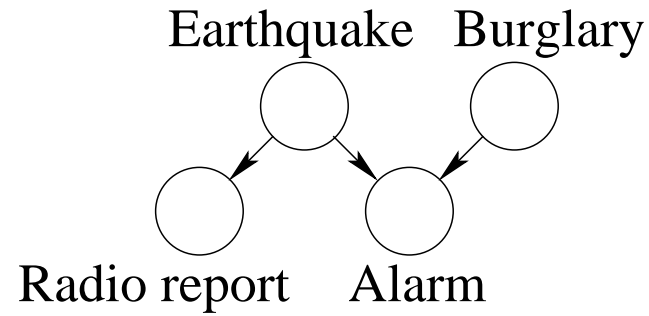
Explaining away phenomenon

- Model

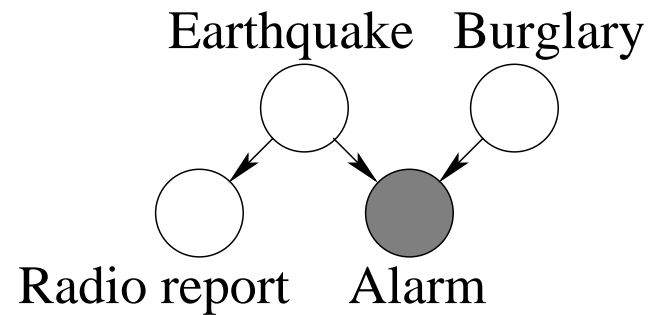


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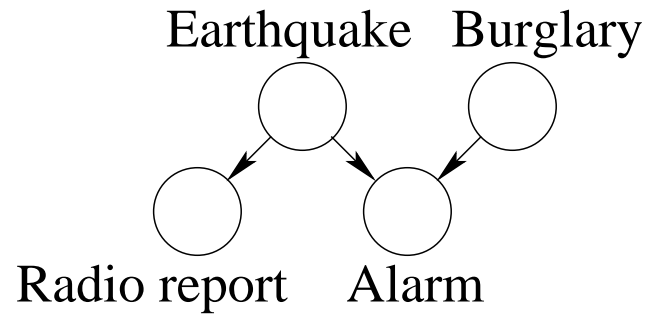


- Evidence, competing causes

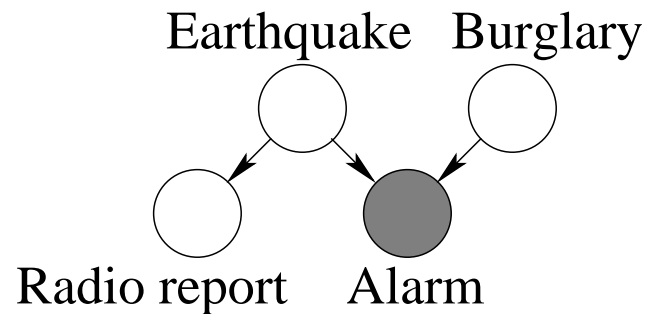


Explaining away phenomenon

- Model



- Evidence, competing causes



- Additional evidence and explaining away

