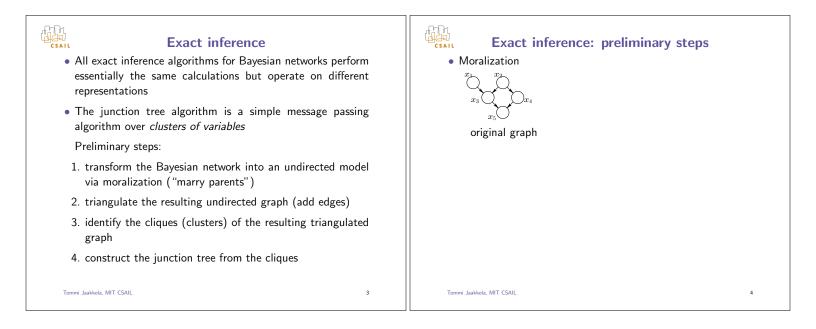
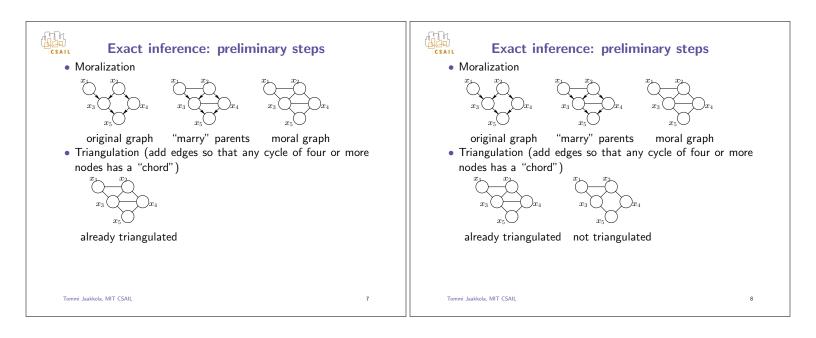
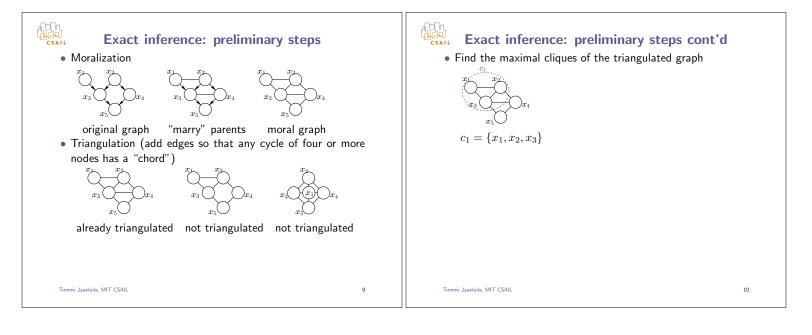
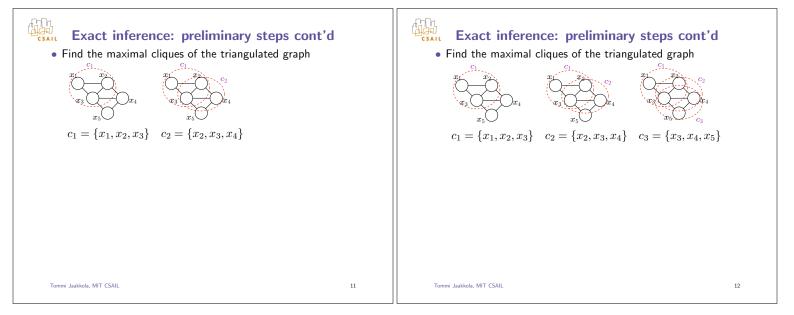
Machine learning: lecture 23 Tommi S. Jaakkola MIT CSAIL tommi@csail.mit.edu	<ul> <li>Course evaluations on-going</li> <li>Project submission (Friday Dec 3): <ul> <li>only electronic submissions (pdf or ps); see the course website</li> <li>if you need an extension (and have a reason), you need to ask. Late submissions are not possible otherwise.</li> </ul> </li> <li>Final exam, in class (Wed Dec 8): <ul> <li>a part of the lecture on Monday Dec 6 will be review</li> <li>comprehensive (covers all the course material) but the emphasis will be on the material since the midterm</li> <li>as promised, EM and HMMs will be on the exam</li> <li>open book, laptops fine if not connected</li> </ul> </li> </ul>
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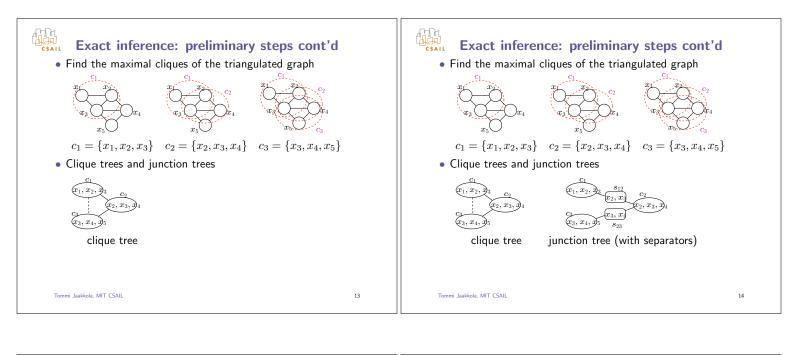


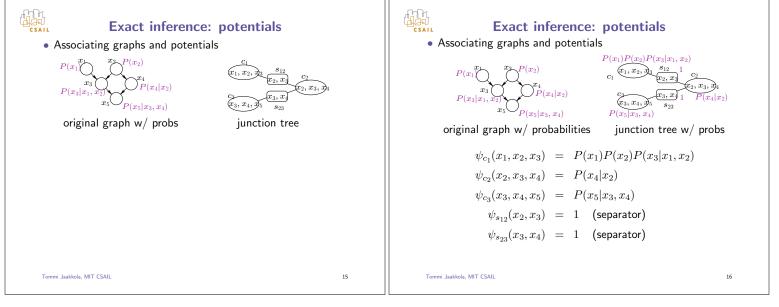
• Moralization $x_{3} \xrightarrow{x_{2}} x_{4}$ • $x_{5} \xrightarrow{x_{2}} x_{4}$	• Moralization $x_1$ $x_2$ $x_3$ $x_4$ $x_2$ $x_4$ $x_5$ $x_4$ $x_5$ $x_4$ $x_5$ $x_4$ $x_5$ $x_4$
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Tommi Jaakkola, MIT CSAIL 5	Tommi Jaakkola, MIT CSAIL 6

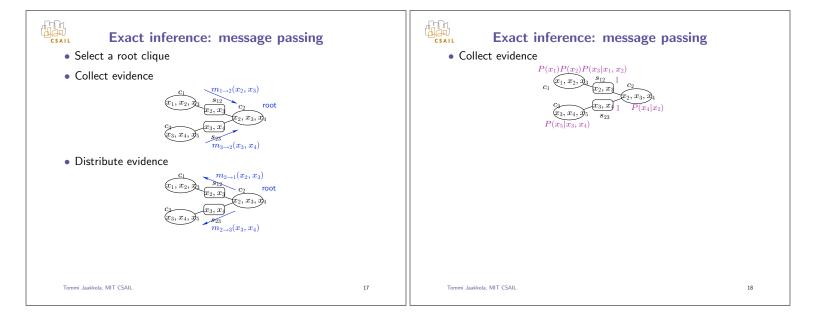


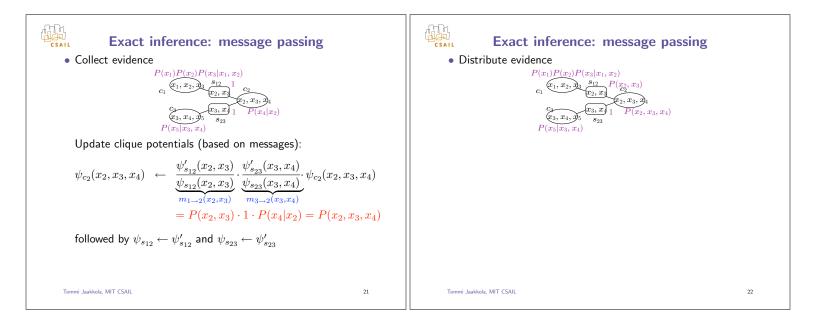


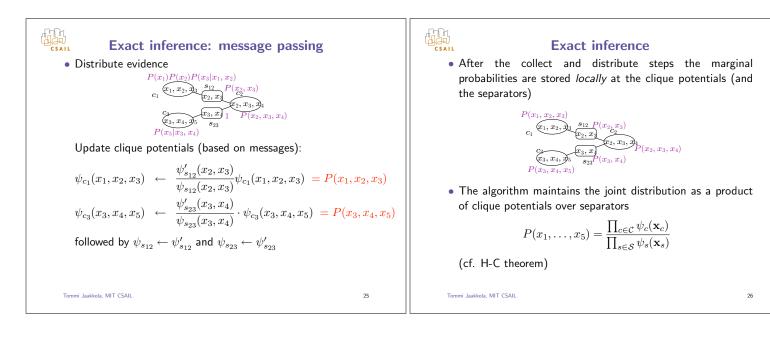


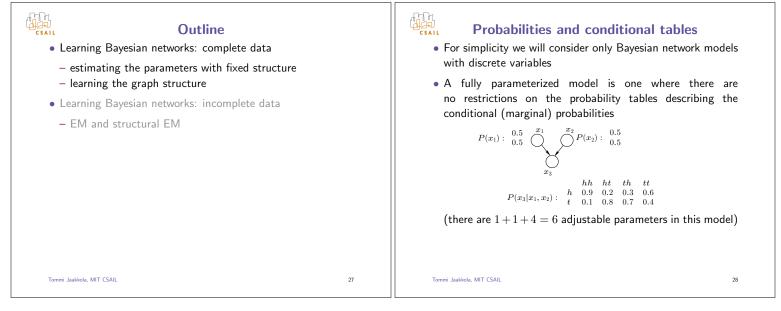












## 

#### Likelihood and complete data

• When the observed data points are complete, the likelihood can be decomposed into a product of terms involving only each conditional table:

$$\begin{split} P(D|G,\theta) &= \prod_{t=1}^{n} P(x_1^t) P(x_2^t) P(x_3^t|x_1^t, x_2^t) \\ &= \prod_{x_1} P(x_1)^{N(x_1)} \times \prod_{x_2} P(x_2)^{N(x_2)} \\ &\times \prod_{x_1, x_2, x_3} P(x_3|x_1, x_2)^{N(x_1, x_2, x_3)} \end{split}$$

#### Likel

#### Likelihood and complete data

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$$P(D|G,\theta) = \prod_{t=1}^{n} P(x_1^t) P(x_2^t) P(x_3^t|x_1^t, x_2^t)$$
  
= 
$$\prod_{x_1} P(x_1)^{N(x_1)} \times \prod_{x_2} P(x_2)^{N(x_2)}$$
  
$$\times \prod_{x_1,x_2} \prod_{x_3} P(x_3|x_1, x_2)^{N(x_1,x_2,x_3)}$$

Each conditional table such as  $P(x_3|x_1, x_2)$  for a fixed  $x_1$  and  $x_2$ , can be estimated separately based on the observed counts such as  $N(x_1, x_2, x_3)$ .

# 

### ML parameter estimates

• Let  $\theta_{\cdot|x_1,x_2}=\{\theta_{1|x_1,x_2},\ldots,\theta_{m|x_1,x_2}\}$  be the parameters defining the conditional table so that

$$P(x_3|x_1, x_2) = \theta_{x_3|x_1, x_2}$$

- where  $\sum_{x_3=1}^{m} \theta_{x_3|x_1,x_2} = 1$  for all values of  $x_1$  and  $x_2$ .
- The ML estimates of these parameters are simply normalized counts (cf. Markov models):

$$\hat{\theta}_{x_3|x_1,x_2} = \frac{N(x_1,x_2,x_3)}{N(x_1,x_2)}$$

where  $N(x_1, x_2) = \sum_{x_3} N(x_1, x_2, x_3).$ 

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