



Machine learning: lecture 24

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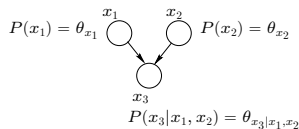
Outline

- Learning Bayesian networks: complete data
 - estimating the parameters with fixed structure
 - learning the graph structure
- Learning Bayesian networks: incomplete data
 - EM and structural EM
- Review



Probabilities and conditional tables

- Simple example: three discrete variables, each taking m possible values



We assume that the model is fully parameterized in the sense that $\{\theta_{x_1}\}$, $\{\theta_{x_2}\}$, and $\{\theta_{x_3|x_1, x_2}$ for each distinct configuration of x_1 and $x_2\}$ are unrestricted and can be chosen independently of each other.



Likelihood and complete data

- When the observed data points are complete, the likelihood has a simple form:

$$\begin{aligned}
 P(D|G, \theta) &= \prod_{t=1}^n P(x_1^t)P(x_2^t)P(x_3^t|x_1^t, x_2^t) \\
 &= \left(\prod_{x_1} P(x_1)^{N(x_1)} \right) \times \left(\prod_{x_2} P(x_2)^{N(x_2)} \right) \\
 &\quad \times \prod_{x_1, x_2} \left(\prod_{x_3} P(x_3|x_1, x_2)^{N(x_1, x_2, x_3)} \right)
 \end{aligned}$$



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 &\quad \times \prod_{x_1, x_2} \left(\prod_{x_3} \theta_{x_3|x_1, x_2}^{N(x_1, x_2, x_3)} \right)
 \end{aligned}$$

Each conditional table such as $\theta_{x_3|x_1, x_2}$ for a fixed x_1 and x_2 , can be estimated separately based on the observed counts $N(x_1, x_2, x_3)$.



ML parameter estimates

$$\begin{aligned}
 P(D|G, \theta) &= \left(\prod_{x_1} \theta_{x_1}^{N(x_1)} \right) \times \left(\prod_{x_2} \theta_{x_2}^{N(x_2)} \right) \\
 &\quad \times \prod_{x_1, x_2} \left(\prod_{x_3} \theta_{x_3|x_1, x_2}^{N(x_1, x_2, x_3)} \right)
 \end{aligned}$$

- The maximum likelihood estimates of parameters $\theta_{\cdot|x_1, x_2} = \{\theta_{1|x_1, x_2}, \dots, \theta_{m|x_1, x_2}\}$ for each fixed configuration of x_1 and x_2 are simply normalized counts (cf. Markov models):

$$\hat{\theta}_{x_3|x_1, x_2} = \frac{N(x_1, x_2, x_3)}{N(x_1, x_2)}$$

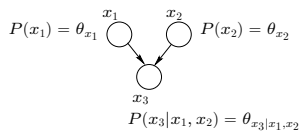
where $N(x_1, x_2) = \sum_{x_3} N(x_1, x_2, x_3)$.



Bayesian estimates: the prior

- We introduce independent priors, e.g., $P_3(\theta_{\cdot|x_1,x_2})$, across variables and for each distinct configuration of the parents

$$P(\theta|G) = P_1(\theta) \times P_2(\theta) \times \prod_{x_1,x_2} P_3(\theta_{\cdot|x_1,x_2})$$



Bayesian estimates: the prior

- We introduce independent priors, e.g., $P_3(\theta_{\cdot|x_1,x_2})$, across variables and for each distinct configuration of the parents
- Moreover, we assume that these priors are Dirichlet:

$$P_3(\theta_{\cdot|x_1,x_2}) = \frac{1}{Z'} \prod_{x_3} \theta_{x_3|x_1,x_2}^{N'(x_1,x_2,x_3)-1}$$

with hyper-parameters (parameters of the prior) $N'(x_1, x_2, x_3) \geq 0$, interpreted as prior "counts".



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This prior is concentrated around

$$\theta'_{x_3|x_1,x_2} = \frac{N'(x_1, x_2, x_3)}{N'(x_1, x_2)}$$

where $N'(x_1, x_2) = \sum_{x_3} N'(x_1, x_2, x_3)$, and more so for larger values of $N'(x_1, x_2)$.



Bayesian estimates: the posterior

- The posterior is also Dirichlet

$$P_3(\theta_{\cdot|x_1,x_2}|D) \propto \overbrace{\prod_{x_3} \theta_{x_3|x_1,x_2}^{N(x_1,x_2,x_3)}}^{\text{likelihood}} \cdot \overbrace{\prod_{x_3} \theta_{x_3|x_1,x_2}^{N'(x_1,x_2,x_3)-1}}^{\text{prior}}$$

$$= \frac{1}{Z} \prod_{x_3} \theta_{x_3|x_1,x_2}^{N'(x_1,x_2,x_3)+N(x_1,x_2,x_3)-1}$$

with hyper-parameters $N'(x_1, x_2, x_3) + N(x_1, x_2, x_3)$.



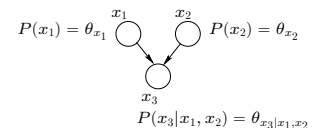
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Bayesian score

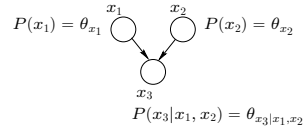
- We can use the marginal likelihood (Bayesian score) as a model (graph) selection criterion:



$$P(D|G) = \int P(D|G, \theta) P(\theta|G) d\theta$$

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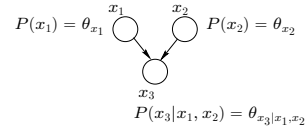
- The form of the likelihood and the prior

$$P(D|G, \theta) = \prod_{x_1} \theta_{x_1}^{N(x_1)} \times \prod_{x_2} \theta_{x_2}^{N(x_2)} \times \prod_{x_1, x_2} \prod_{x_3} \theta_{x_3|x_1, x_2}^{N(x_1, x_2, x_3)}$$

$$P(\theta|G) \propto \underbrace{\prod_{x_1} \theta_{x_1}^{N'(x_1)}}_{P_1(\theta)} \times \underbrace{\prod_{x_2} \theta_{x_2}^{N'(x_2)}}_{P_2(\theta)} \times \underbrace{\prod_{x_1, x_2} \prod_{x_3} \theta_{x_3|x_1, x_2}^{N'(x_1, x_2, x_3)}}_{P_3(\theta_{x_3|x_1, x_2})}$$

permit us to evaluate the Bayesian score locally.

Bayesian score: graphs



- The Bayesian score reduces to a product of local terms:

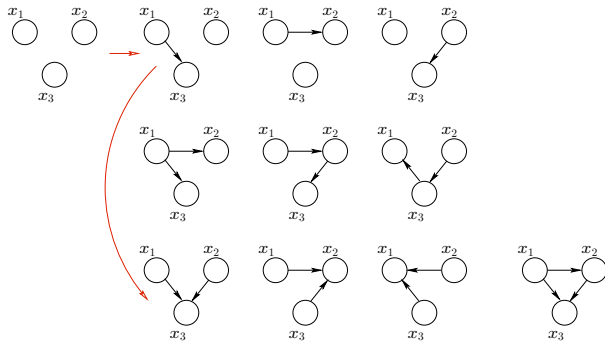
$$P(D|G) = \int P(D|G, \theta) P(\theta|G) d\theta$$

$$= \int \left[\prod_{x_1} \theta_{x_1}^{N(x_1)} \times \prod_{x_2} \theta_{x_2}^{N(x_2)} \times \prod_{x_1, x_2} \prod_{x_3} \theta_{x_3|x_1, x_2}^{N(x_1, x_2, x_3)} \right] P(\theta|G) d\theta$$

$$= P(D_1|G) \times P(D_2|G) \times \prod_{x_1, x_2} P(D_3|x_1, x_2|G)$$

Learning Bayesian networks

- We can perform a greedy search over (equivalence classes of) Bayesian networks based on the score:



Review for the final

- The final is comprehensive
- Major concepts
 - regression, active learning
 - classification, margins, kernels, feature selection
 - over-fitting, regularization, generalization, model selection
 - latent variable models, estimation with incomplete data
 - clustering, objectives
 - graphs and probabilities, inference