## NTT9904-01: Human-Robot Dynamic Social Interaction

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**Project Overview** 



## The big question:

**s humans naturally interact with an embodied robot** 

s is the physical nature ultimately important, or will a person have identical reactions to an equivalently programmed 3-D graphical agent?

MIT s role: provide a physically embodied robot that can enter into dynamic interactions with a person.

NTT s role: measure the physiological response of people interacting with the robot and interacting with a 3-D graphical agent and compare them.



