

A Forest of Sensors: Using adaptive tracking to classify and monitor activities

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A Forest of Sensors

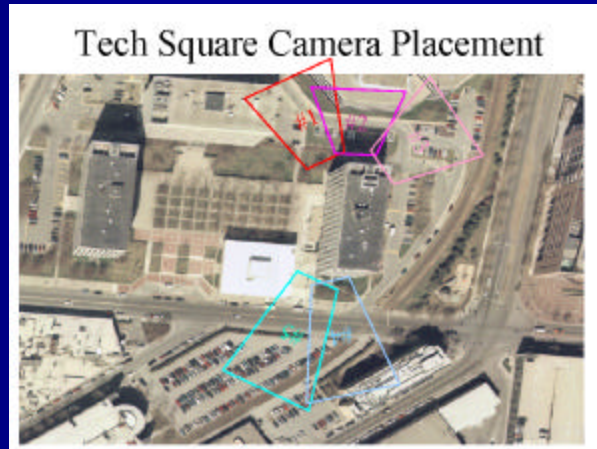
- Given autonomous vision modules (AVMs): low power, low cost, can compute wide range of visual routines
- Create a forest of disposable AVMs:
 - attached to trees, buildings, vehicles
- Question: Can the forest bootstrap itself to monitor sites for activities?

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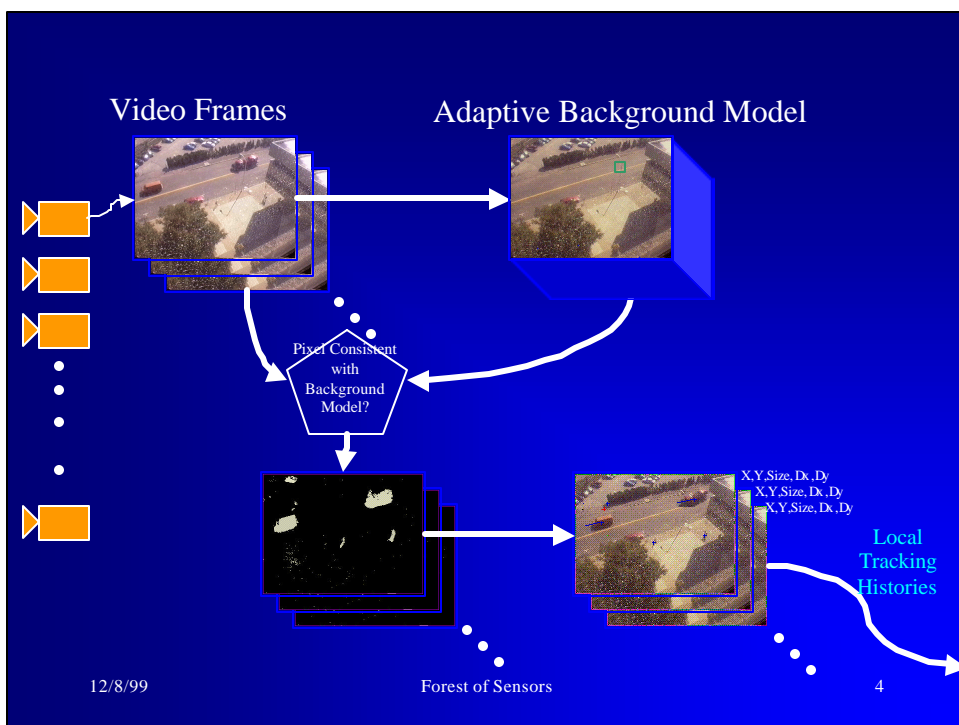
Multi-camera version



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Capabilities and components

- Self calibration
- building rough site models
- detecting visibility
- primitive detection
- moving object modeling
- activity detection
- activity calibration

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Working hypothesis

- Can achieve all of these capabilities simply by accurately tracking moving objects in the scene.

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A robust, real-time tracker

- Model each pixel as an independent process
- Model previous n samples with weighted mixture of Gaussians, using exponentially decaying time window
- Background defined as set of dominant models that account for T percent of data
- Update weights and parameters
- Pixel > 2 sigma from background is moving
- Select significant blobs as objects

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Adaptive tracking



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Dynamic calibration

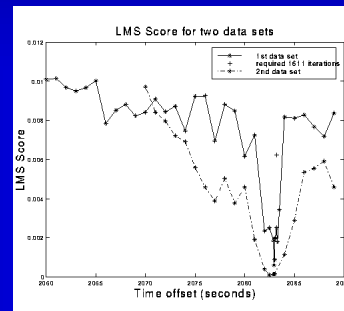
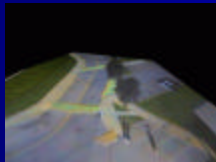
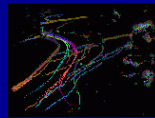
- Track objects in multiple cameras
- use correspondences to find a homography, assuming planar motion
- modify homography by fitting image features
- use non-planar features to solve for epipolar geometry, and refine

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Dynamic calibration



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Site modeling

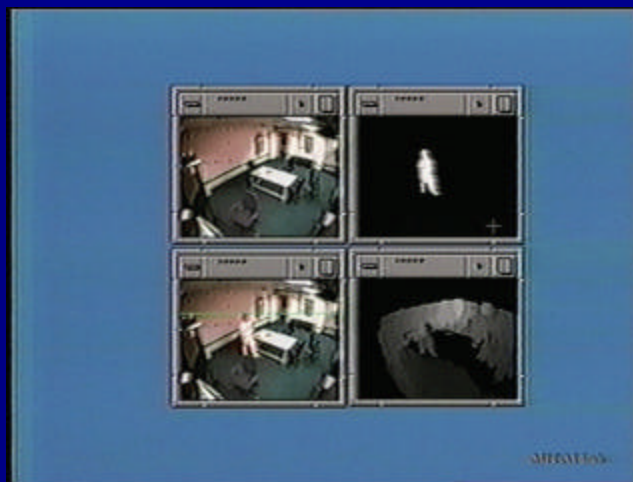
- N camera stereo from calibration
- dynamic tracking updates
- visibility detection and placement update
- reconstruction from multiple moving views

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Site models by tracking



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Site models by tracking



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Site modeling from stereo

- Multi-camera stereo reconstruction



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Stereo reconstruction



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Activity detection & calibration

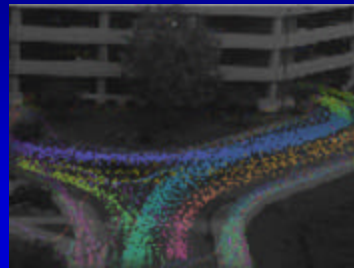
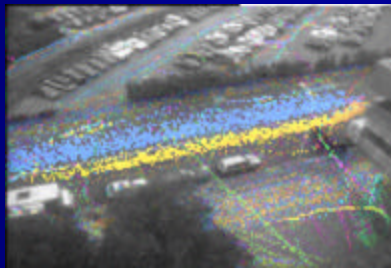
- Need to find common patterns in track data

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Pattern tracks

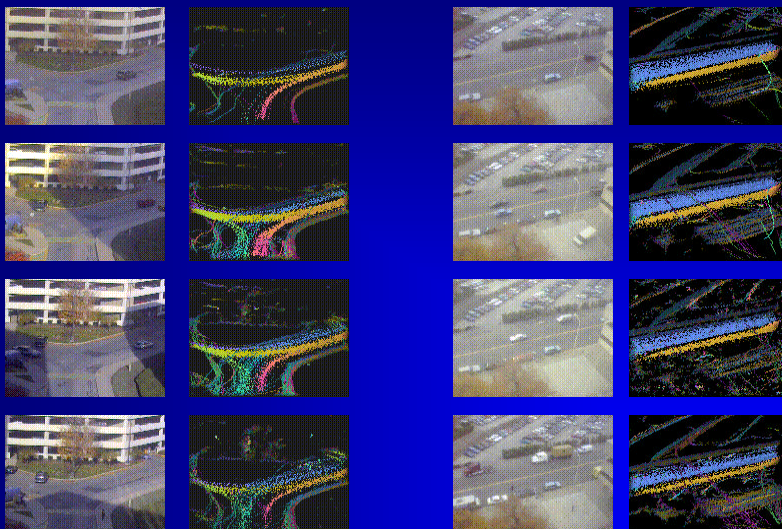


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Detect Regularities & Anomalies?



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Example track patterns

- Running continuously for almost 1 year
 - during snow, wind, rain, ...
- one can observe patterns over space and over time
- need a system to detect automatically

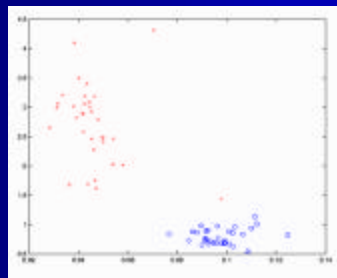
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Classifying objects

- Simple classifiers based on feature selection



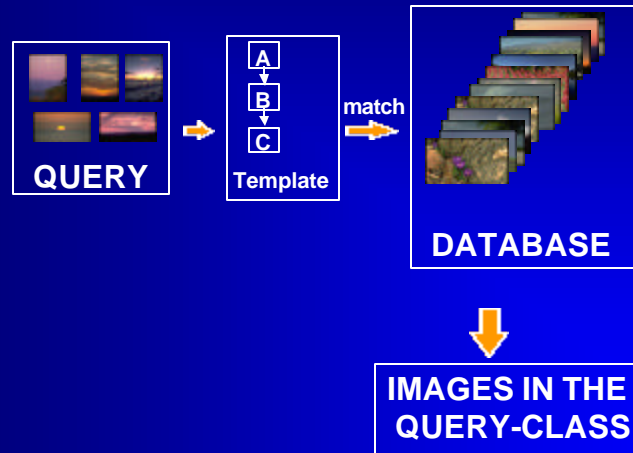
Example -- people vs.
cars using aspect ratio
and size

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Flexible template querying



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Example

- Detection



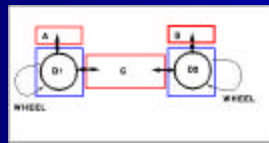
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Classifying objects

- Using flexible templates to detect vehicles



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Classifying activities

- Quantize state space of continuous observations by fitting Gaussians
- map sequence of observables to sequence of labels
- compute co-occurrence of labels over sequences -- defines joint probability
- cluster by E/M methods to find underlying probability distributions

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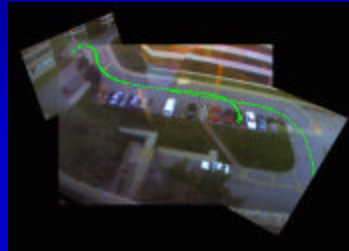
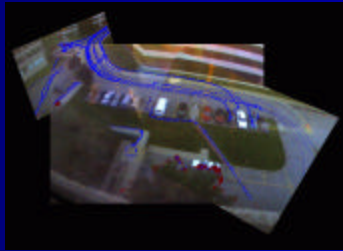
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An aerial photograph of a city street intersection. A colorful, abstract graphic overlay is present, consisting of a central point from which several lines radiate outwards in various directions. The lines are colored in shades of red, orange, yellow, green, and blue. The background shows a city street with buildings, trees, and a road. The graphic appears to be a stylized representation of a network or a path.

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Multi-camera coordination

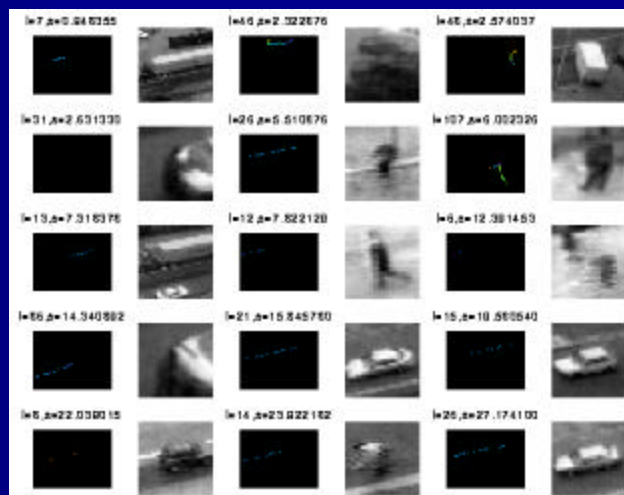


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Finding unusual events

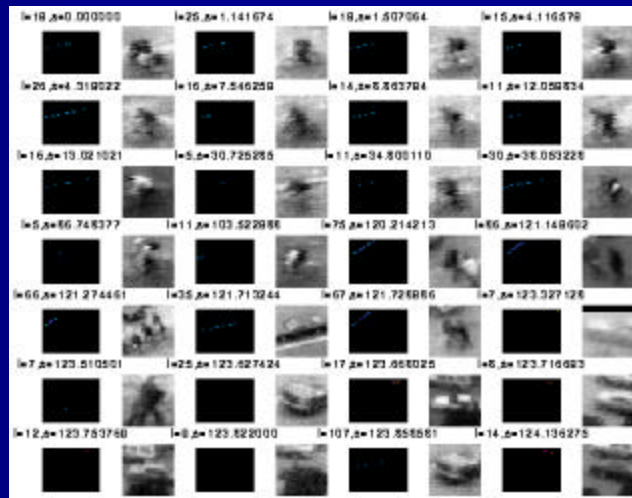


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Finding similar events



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Future plans

- integration of pieces
- site models from dynamic tracking
- activity classification from multiple views
- variations on classification methods
- vocabulary of activities and interactions
- interactions of activity tracks
- fine scale actions

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